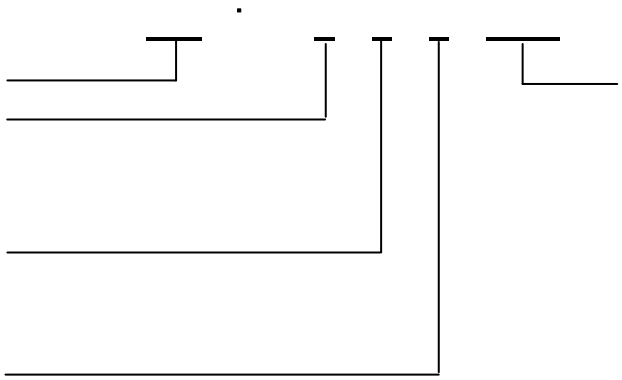
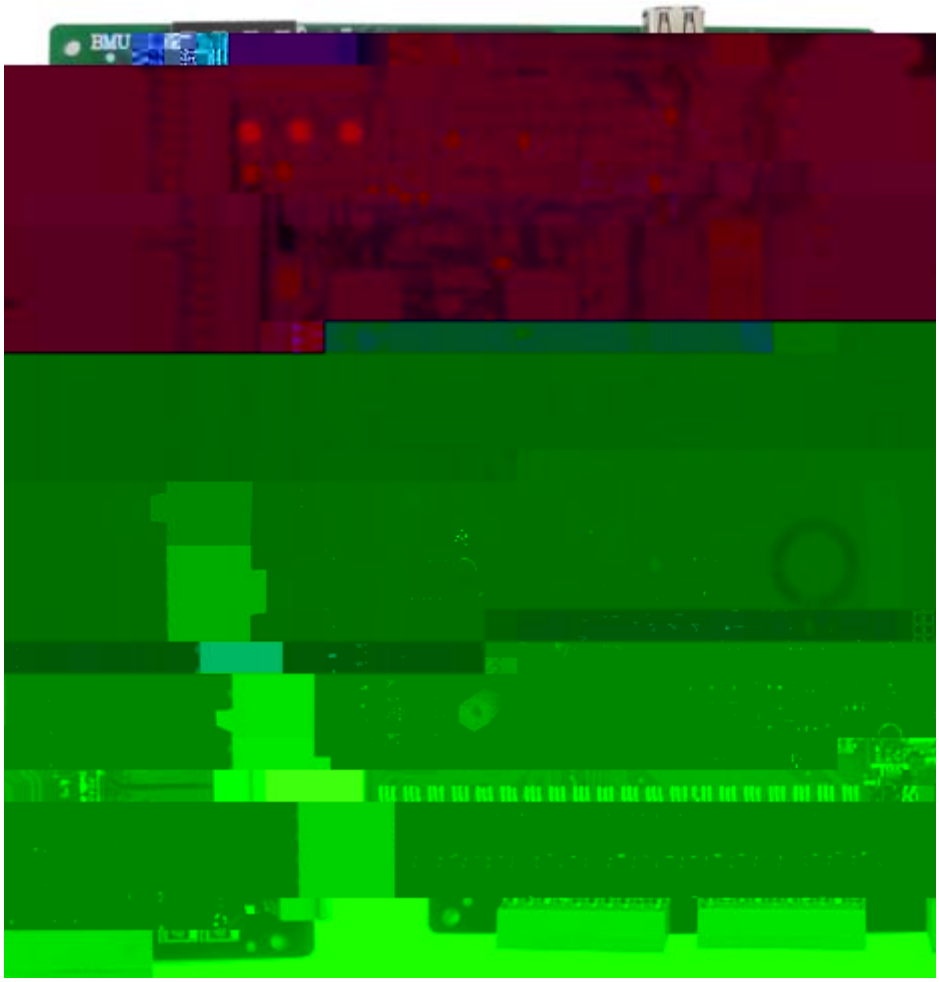
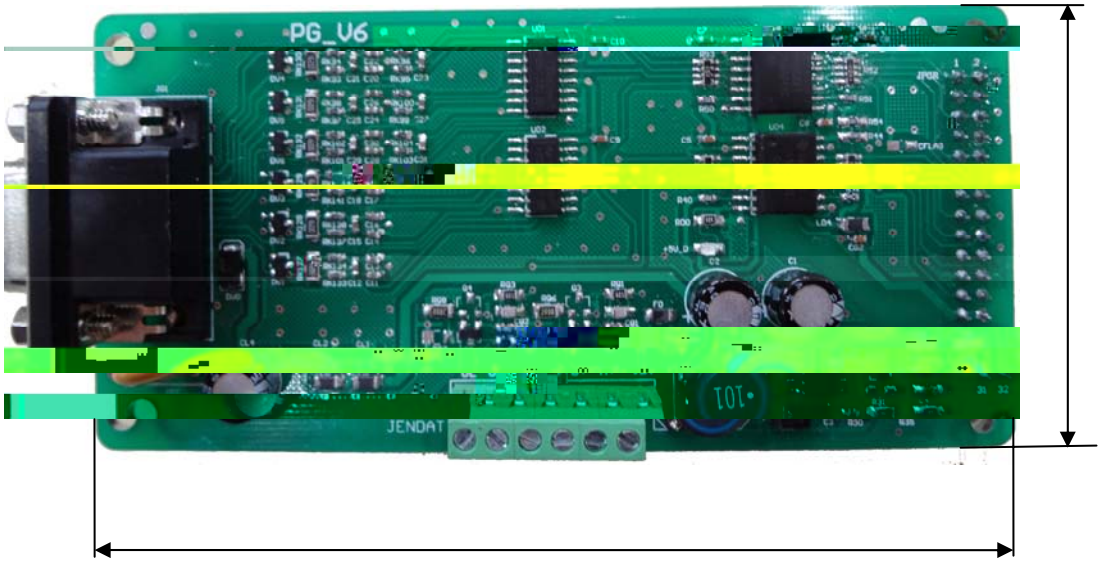


CHART 1 SPECIFICATIONS

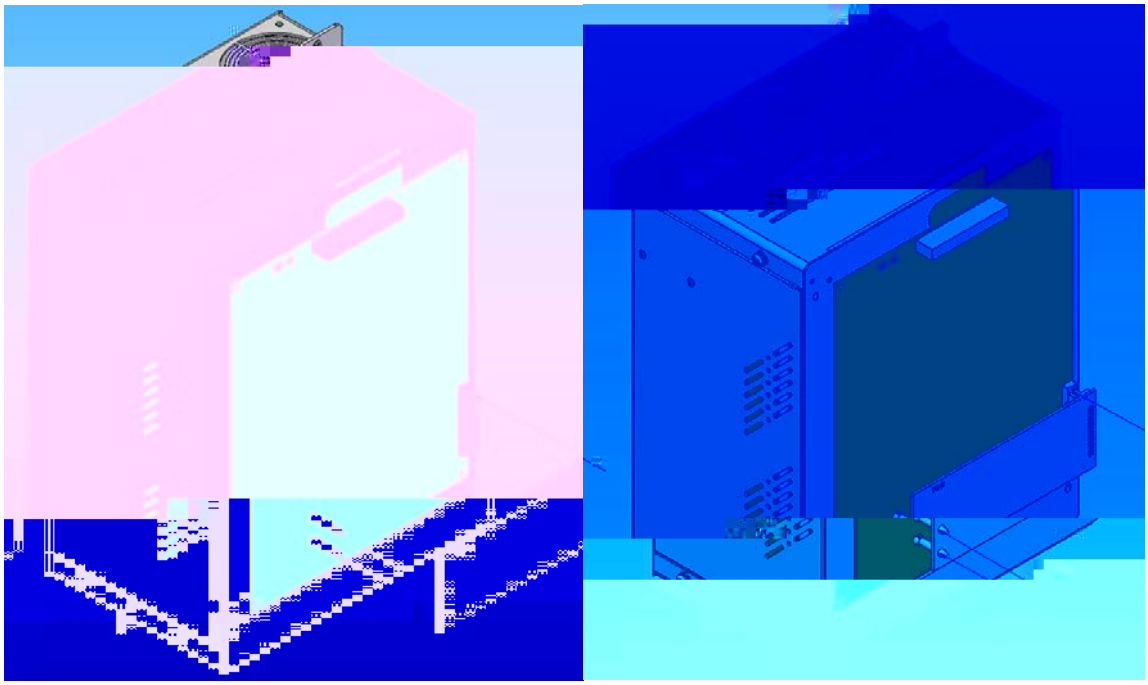
		。 。


BMU


PG_V6
JENDAT

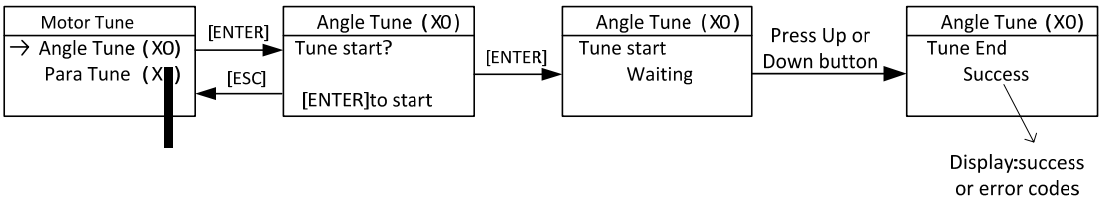


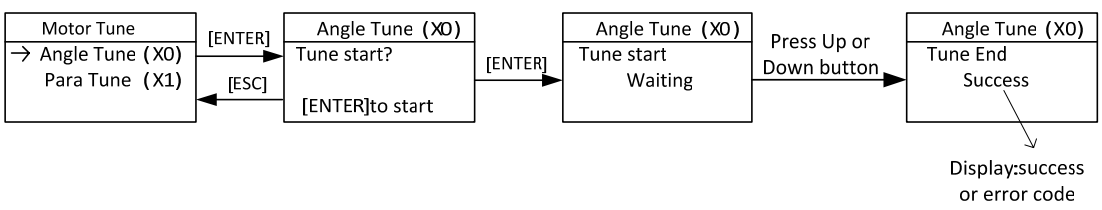
.



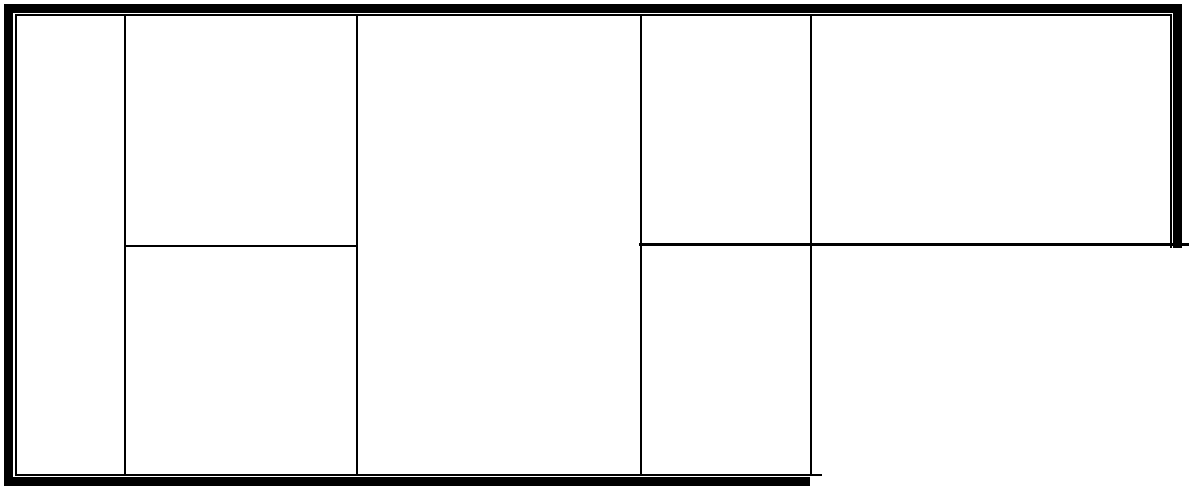
'

				0


Motor Tune
→ Angle Tune (X0)
Para Tune (X1)
[ENTER]
[ESC]
Angle Tune (X0)
Tune start?
[ENTER]to start
[ENTER]
Angle Tune (X0)
Tune start
Waiting
Press Up or
Down button
Angle Tune (X0)
Tune End
Success
Display:success
or error codes

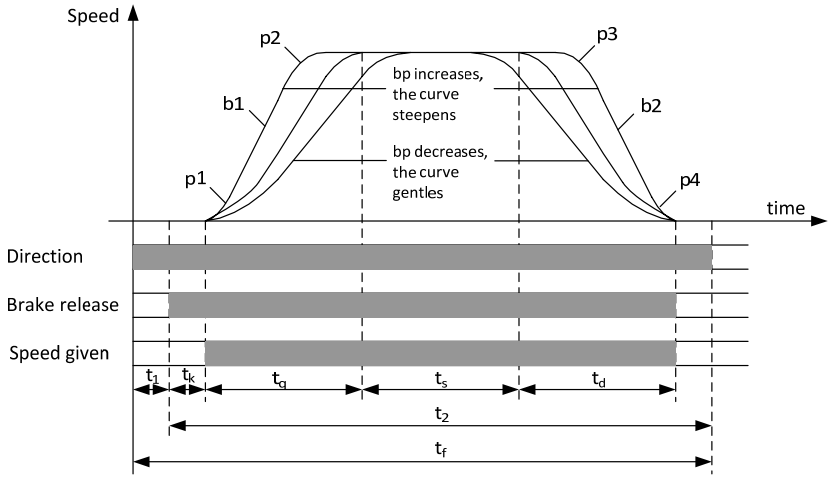

Motor Tune
→ Angle Tune (X0)
Para Tune (X1)
[ENTER]
[ESC]
Angle Tune (X0)
Tune start?
[ENTER]to start
[ENTER]
Angle Tune (X0)
Tune start
Waiting
Press Up or
Down button
Angle Tune (X0)
Tune End
Success
Display:success
or error code

	صر			
	لہ			



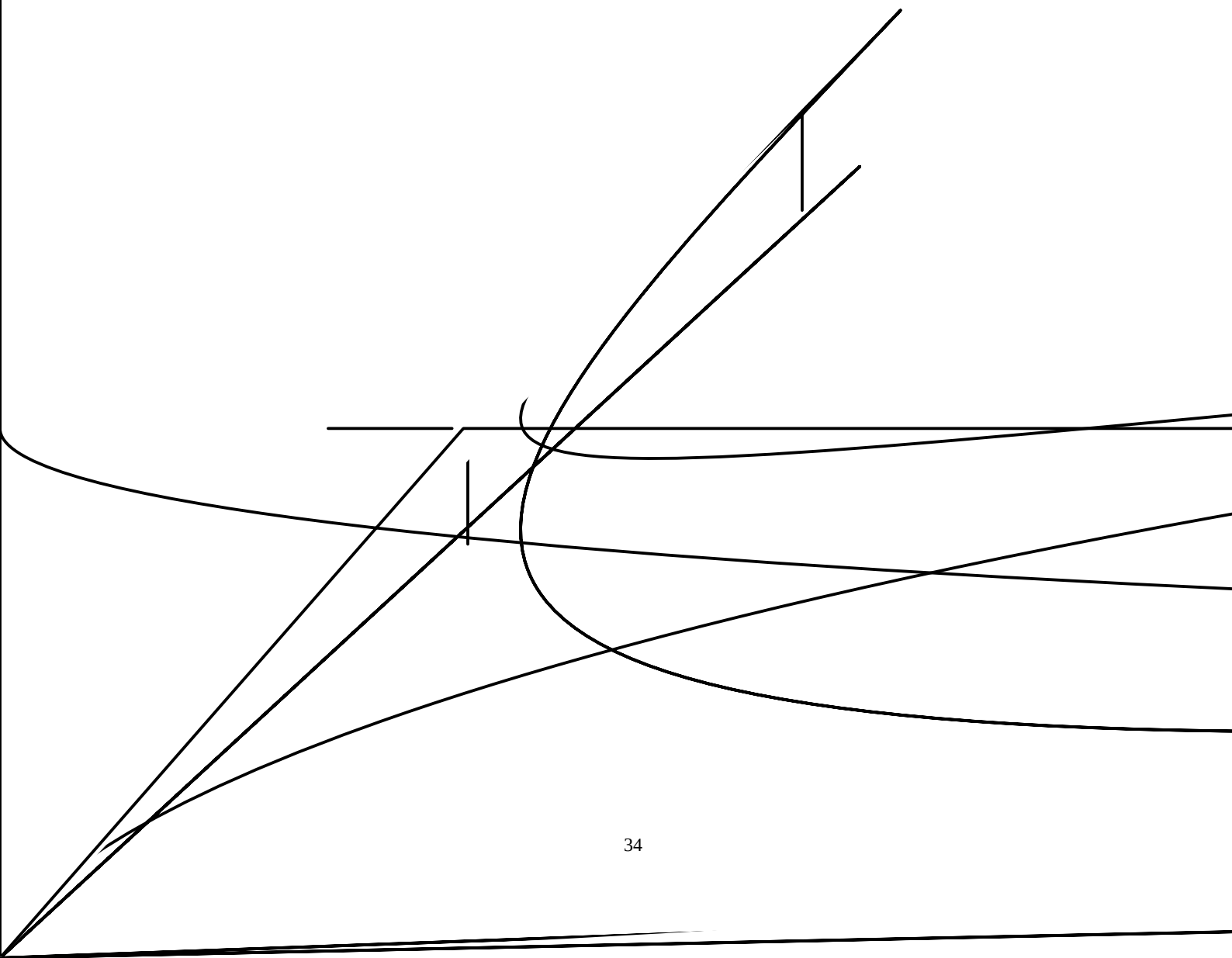
	g						

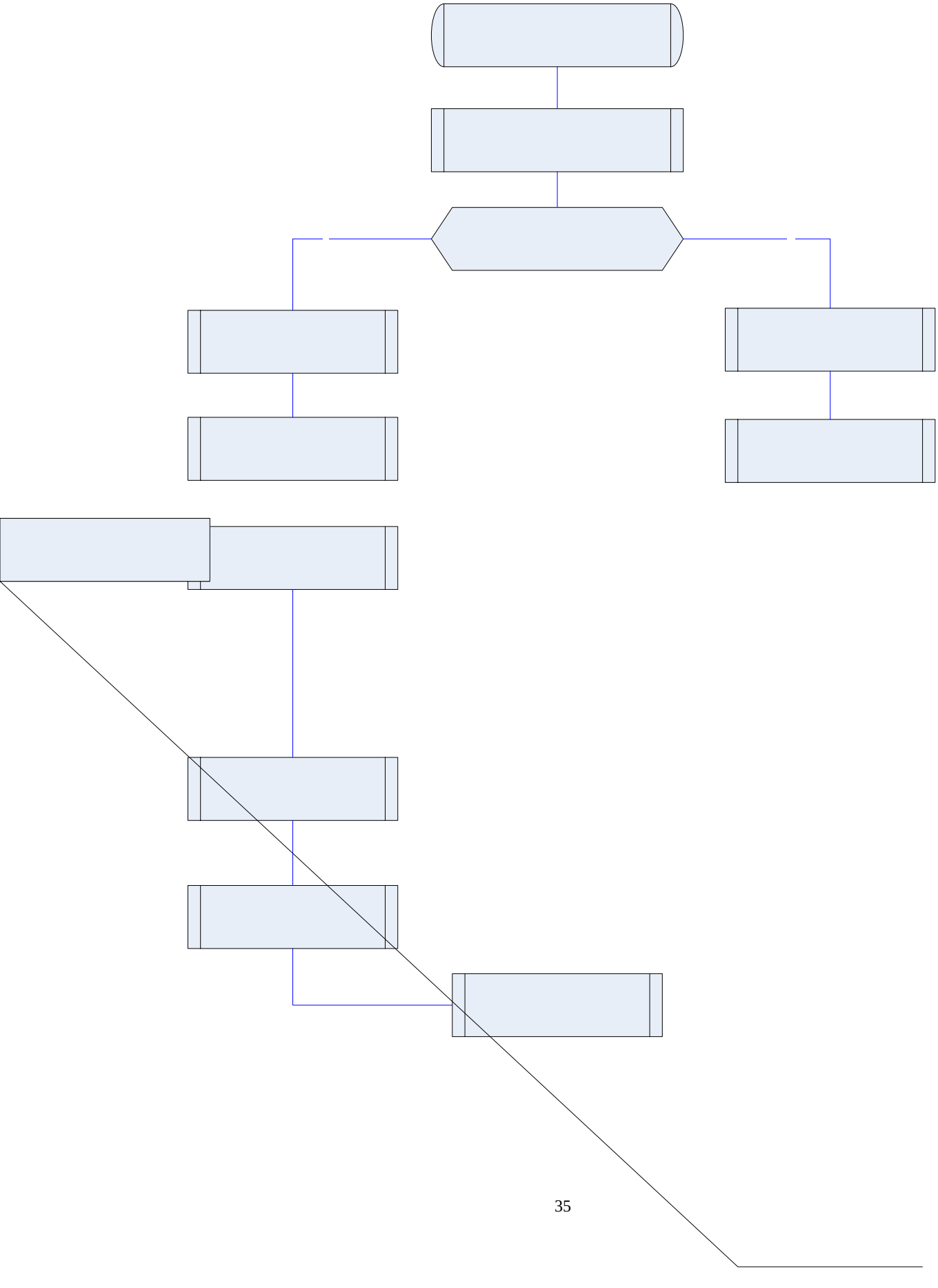
		▲

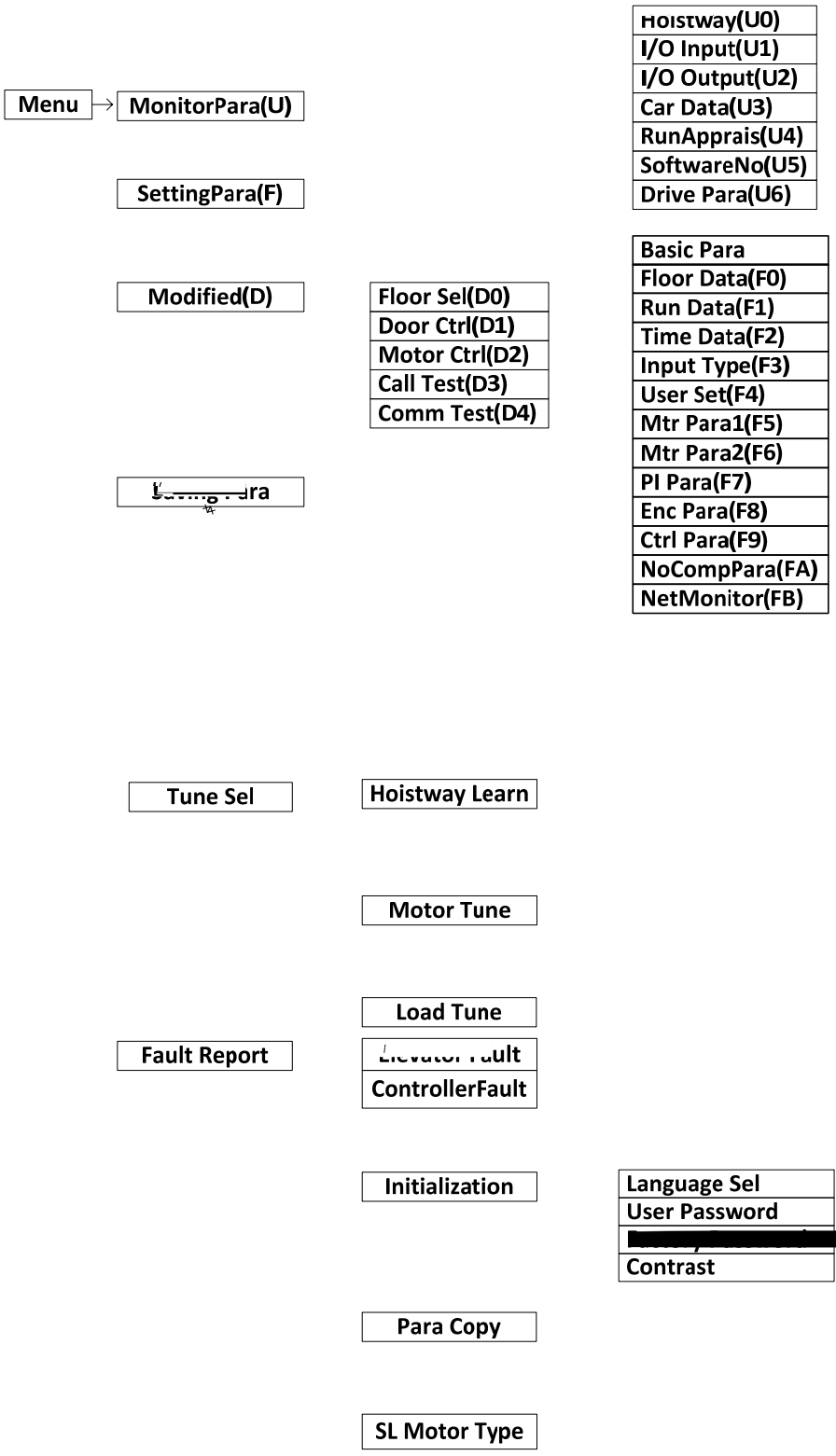


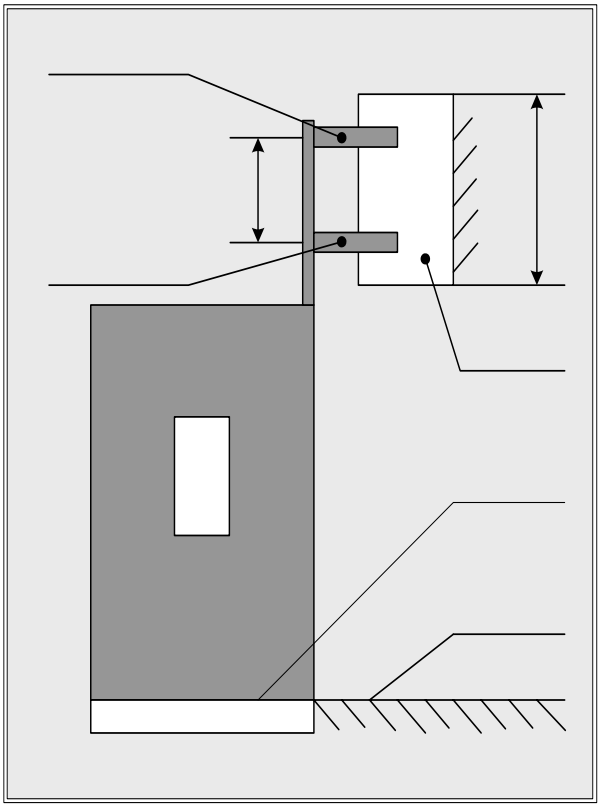
t_1 Direction forming time
t_2 Direction keeping time
t_k Advanced time for brake release
t_s Running time at constant speed
t_q Acceleration time at starting
t_d Deceleration time at braking
t_f One cycle of running

≤






Menu
MonitorPara(U)
SettingPara(F)
Modified(D)
Tune Sel
Fault Report
Initialization
Para Copy
SL Motor Type
Hoistway Learn
Motor Tune
Load Tune
ControllerFault
Floor Sel(D0)
Door Ctrl(D1)
Motor Ctrl(D2)
Call Test(D3)
Comm Test(D4)
Hoistway(U0)
I/O Input(U1)
I/O Output(U2)
Car Data(U3)
RunApprais(U4)
SoftwareNo(U5)
Drive Para(U6)
Basic Para
Floor Data(F0)
Run Data(F1)
Time Data(F2)
Input Type(F3)
User Set(F4)
Mtr Para1(F5)
Mtr Para2(F6)
PI Para(F7)
Enc Para(F8)
Ctrl Para(F9)
NoCompPara(FA)
NetMonitor(FB)
Language Sel
User Password
Contrast



Ë

Ë

Ë Ë

Ë

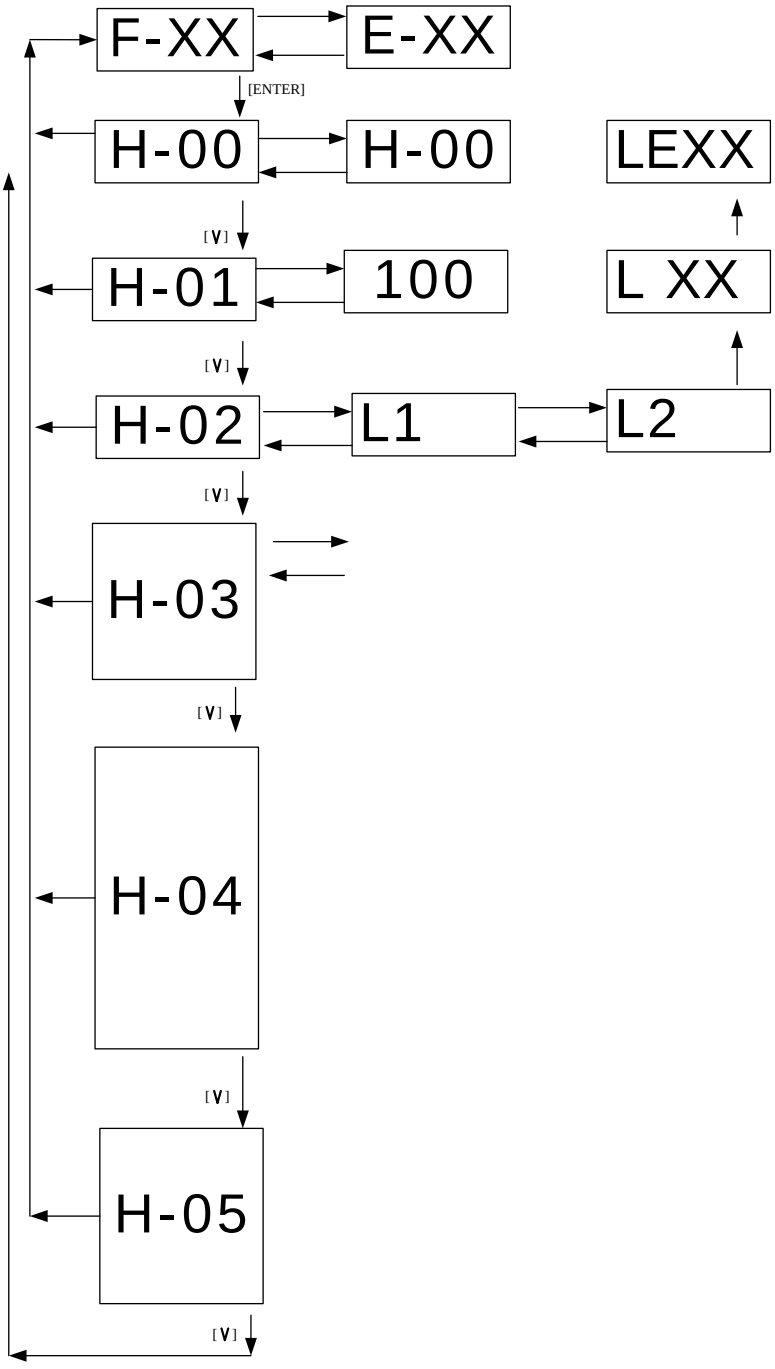
	Ю Æ 2			--
	Э Æ 2			--

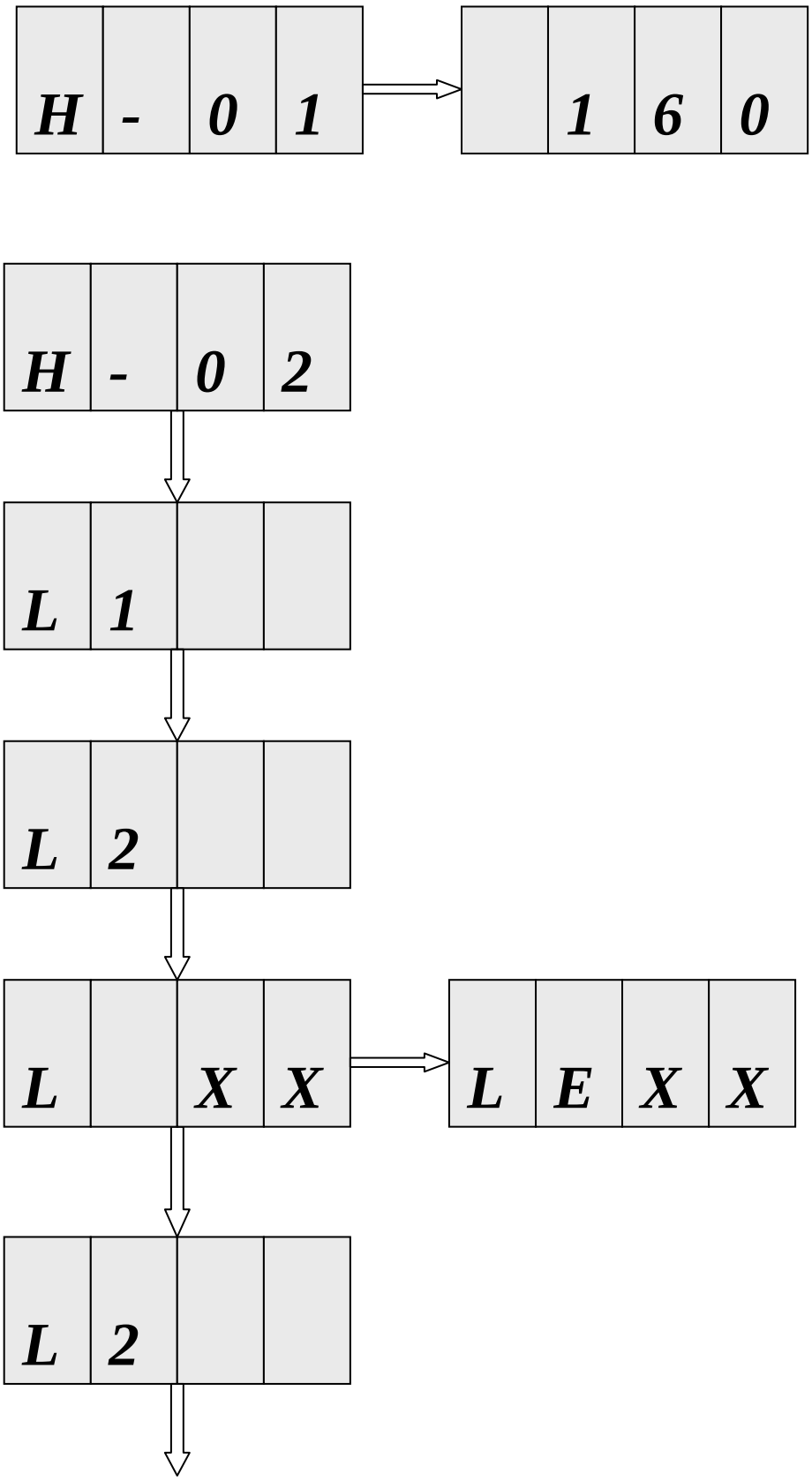
Hour --

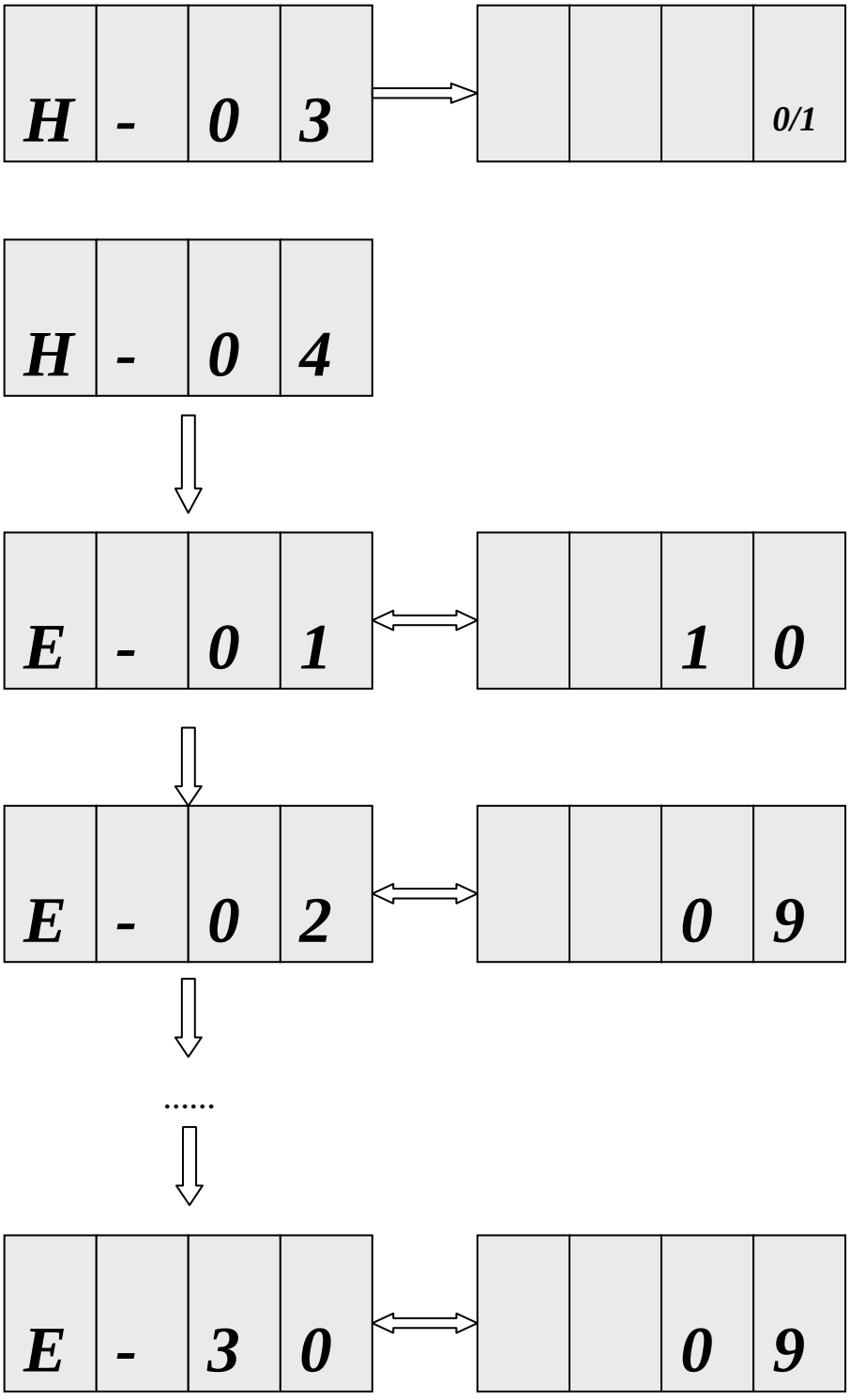
	a ṃ				
	a ṃ				
	↓ a ṃ				
	↓ a ṃ				
	ṁ				
	⁄				
	⊥				
	⊥				

	صر		.			

لـ


F-XX
E-XX
[ENTER]
H-00
H-00
LEXX
[V]
H-01
100
L XX
[V]
H-02
L1
L2
[V]
H-03
[V]
H-04
[V]
H-05
[V]


H - 0 1
1 6 0
H - 0 2
L 1
L 2
L X X
L E X X
L 2


H - 0 3
0/1
H - 0 4
E - 0 1
1 0
E - 0 2
0 9
.....
E - 3 0
0 9